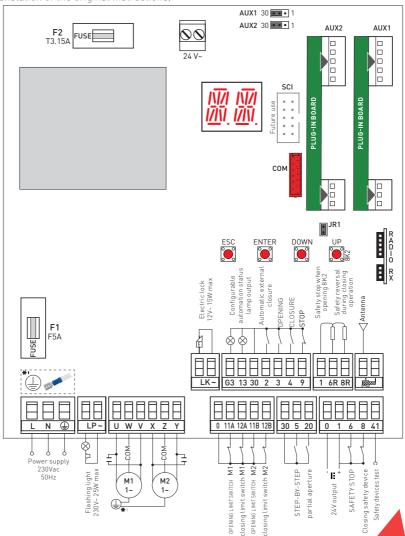


IP2354EN • 2020-07-10

# **Ditec LCA80**

Control panel installation manual for automations with one or two 230V~ motors

(translation of the original instructions)



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This symbol indicates instructions or notes regarding safety, to which special attention must be paid.

i

This symbol indicates useful information for the correct operation of the product.

Factory settings



# 1. General safety precautions



Failure to observe the information given in this manual may lead to personal injury or damage to the equipment.

## Keep these instructions for future reference

This installation manual is intended for qualified personnel only.

Installation, electrical connections and adjustments must be performed in accordance with Good Working Methods and in compliance with the present standards.

This product must only be used for the specific purpose for which it was designed.

Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use.

Read the instructions carefully before installing the product. Incorrect installation may cause danger.

The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger.

Before installing the product, make sure it is in perfect condition.

Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard.

The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working Methods, installation premises, system operating logic and the forces developed by the automation.

Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply.

Check that there is an adequate residual current circuit breaker and a suitable overcurrent cutout upstream of the electrical installation in accordance with Good Working Methods and with the laws in force.

When requested, connect the automation to an effective earthing system that complies with current safety standards.



During installation, maintenance and repair operations, cut off the power supply before opening the cover to access the electrical parts.

The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorisation device declines all responsibility if component parts not compatible with safe and correct operation are fitted.

Only use original spare parts when repairing or replacing products.





# 1.1 Safety functions

The Ditec LCA80 control panel has the following safety functions:

- obstacle recognition with force limiting.

The maximum response time of the safety functions is 0.5s. The reaction time to a faulty safety function is 0.5s.

The safety functions comply with the standards and performance level indicated below:

EN ISO 13849-1:2015 Category 2 PL=c

The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

# 2. EC Declaration of Conformity

Entrematic Group AB declares that the Ditec LCA80 control panel is compliant with the fundamental requisites and other relevant requirements defined down by the following EC directives:

EMC Directive 2014/30/EU; Low Voltage Directive 2014/35/EU. RoHS Directive 2011/65/EU Landskrona. 10-07-2020

Matteo Fino
(President & OEO)

# 3. Technical specifications

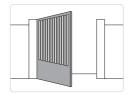
Power supply	230V~ 50Hz	
Power absorption	4A max	
Fuses	F1= F5 A (Motor driver circuits) F2= T3.15 A (Electric lock circuit)	
Motor output	230VAC 50Hz; 2 x 2A max; 1 x 4A max	
Permanent power supply to accessories 0-30	24V = 0.3A max WARNING: the total sum of the	
Power supply to accessories 0-1	24V = 0.3A max current values delivered from the 24V~ outputs 30 and 1 must never	
24V~ accessory power supply	24V~ 0.3A max exceed 0.5A.	
Electric lock output	12V~ 15W (max 3s) 12V~ 0.1A (continuous)	
230V~ flashing light output	25W max	
Ambient temperature	-20°C - +55°C	
Storable radio codes	100/200 see RO $\rightarrow$ MU $\rightarrow$ 10/20 (Paragraph 11.5)	
Dadie frances	433.92MHz (prod. code ZENRS) or 868.35MHz (prod. code ZENPRS).	
Radio frequency	The receiver module is purchasable separately	
Degree of protection of the container	IP55	
Product size	187x261x103mm	

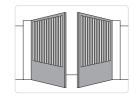


**NOTE**: The given operating and performance features can only be guaranteed with the use of DITEC accessories and safety devices.



# 3.1 Applications





# 4. Installation and electrical connections

- Perforate the relevant points in the bottom part of the box (Fig. 4.1, page 6).
- Fix the control panel firmly in place. You are advised to use convex head screws (max head Ø 10mm) with a cross imprint (the centre distance for the holes is shown in Fig. 4.2, page 6).
- Insert the cable glands and corrugated tubes from the lower side of the container.
- Before connecting the power supply, make sure the plate data correspond to those of the mains power supply.
- An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply.
- Check there is an adequate residual current circuit breaker and overcurrent cutout upstream
  of the electrical system.
- In order to comply with the essential requisites of the Standards in force, reclose the cover once the wires have been connected to the terminals.

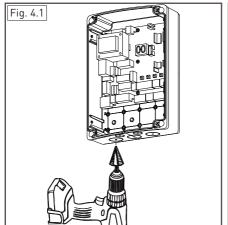


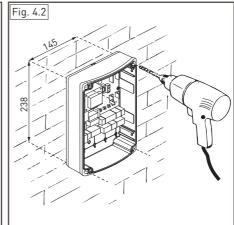
The connections to the mains power supply and to any possible low voltage wires (230V) in the section outside the control panel must be made on an independent channel separated from the connections to the command and safety devices (SELV = Safety Extra Low Voltage). The corrugated tubes must enter the control panel by a few centimetres via the holes on the base box.

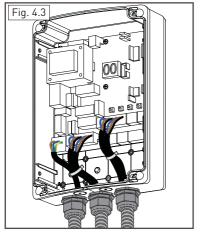
- Make sure there are no sharp edges that may damage the cables.
- Make sure the mains power wires (230V) and the accessory wires (24V) are separated (Fig. 4.3).
- The cables must have dual insulation, be sheathed near the relative connection terminals, and be held in place with ties [B] (not supplied).
- If necessary, fit the clip hinges on the bottom of the box and on the cover (left or right side, as preferred) [Fig. 4.4, page 6].
- After making the adjustments and settings, fix the cover in place with the screws supplied (Fig. 4.5, page 6).

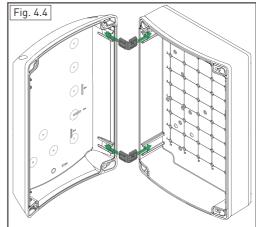


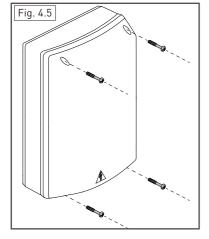












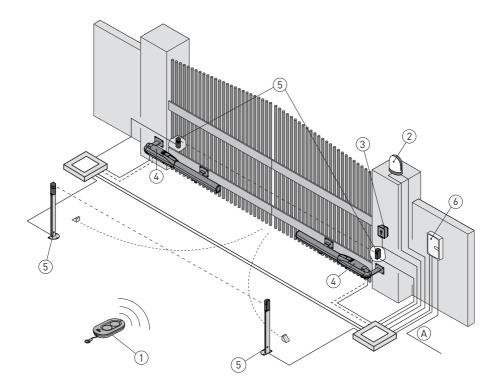
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## 4.1 Maintenance

The control panel doesn't require any special maintenance.

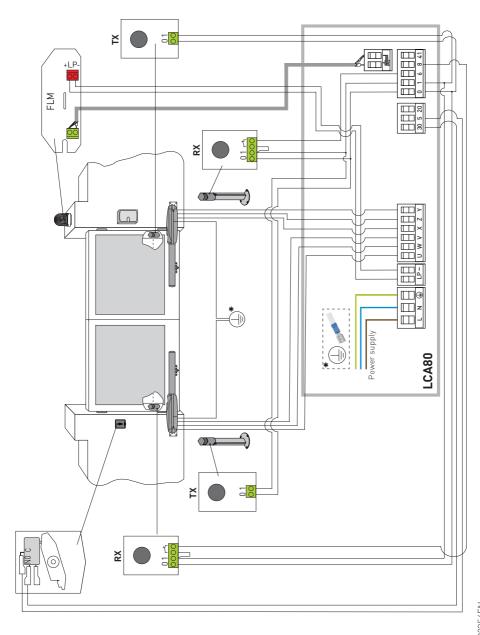
Make regular checks to ensure the seals on the box and the electrical connections are in good condition.

# 4.2 Standard installation



Ref.	Description	Cable
1	Transmitter	/
2	Flashing light	2 x 1mm <sup>2</sup>
	Antenna (integrated in the flashing light)	RG-58 coax cable (50Ω)
3	Key selector switch	4 x 0.5mm <sup>2</sup>
3	Digital combination wireless keypad	/
4	Actuator (motor)	4 x 1.5mm²
4	Extra low voltage limit switch unit (if present)	3 x 0.5mm²
5	Photocells	4 x 0.5mm²
6	Control panel	3G x 1.5mm <sup>2</sup>
Α	Connect the power supply to a certified-compliant omnipolar switch (not included) with a contact opening distance of at least 3 mm.  Connection to the mains must be via an independent channel, separated from the connections to the compand and safety devices.	

# 4.3 Standard installation wiring diagram



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# 5. Commands and safety devices



You are advised to read paragraph 11 for all the details about the possible adjustments.



**WARNING**: terminal 30 (common positive for commands) has the same functions as terminal 1 and for this reason, the commands visible on the display are indicated with 1-5, 1-3, 1-4, etc. However, unlike terminal 1, it is also active when the control panel is in stand by  $E \supset DN$ .



**WARNING**: make a jumper for all NC contacts if not used, or deactivate them via the relative menu. Terminals with the same number are equal.

# 5.1 Command inputs

	Command		Function	Description										
30 -	2	NO	AUTOMATIC CLOSURE	Selecting $\Pi \Gamma \to I$ - $Z$ , the permanent closed state of the contact enables automatic closing.										
			OPENING	When selecting ] [ $\rightarrow$ ] 5 $\rightarrow$ ]- ], the closure of the contact activates an opening operation.										
30 -	3	NO	STEP-BY- STEP	When selecting $\mathbb{C} \to 35 \to 1-5$ , the closure of the contact activates a sequential opening or closing operation: opening-stop-closing-opening. The "opening-stop-closing-opening" sequence can be changed to "opening-stop-closing-stop-opening" by selecting $\mathbb{C} \to PP$ .										
30 -		NO	CLOSURE	Closing of the contact activates a closing operation.										
30 -	5	NO	STEP-BY- STEP	When selecting $\P \  \   \   \   \   \   \   \   \   \$										
														OPENING
30 -	<b>—</b> 9	NC	STOP	The opening of the safety contact causes the current operation to stop. If $\mathbb{RP} - \mathbb{R9} = \mathbb{9P}$ , automatic closure is disabled when contact 30-9 recloses. If $\mathbb{RP} - \mathbb{R9} = \mathbb{9T}$ , automatic closure remains enabled when contact 30-9 recloses.										
30 -	9	NO	"OPERATOR PRESENT" COMMAND	When selecting $\PP \rightarrow R \  \  \rightarrow HR$ , the opening of contact 30-9 enables the "operator present" function: - opening with operator present 30-3 - closure with operator present 30-4 NOTE: any safety devices, automatic closure and plug-in board in the AUX slot are all disabled.										
30 —	20	NO	partial aper- ture	The closure of the contact activates a partial opening operation. Once the automation stops, the partial opening control performs the opposite operation to the one performed before the stop.										

# 5.2 Safety inputs

Command		Function	Description
1 — t 6	NC	SAFETY STOP	For safety devices with self-test input: When selecting $PP \rightarrow D                                $
1 — 1 8	NC	Closing safety device	For safety devices with self-test input: When selecting $PP \rightarrow PP \rightarrow PP \rightarrow PP \rightarrow PP \rightarrow PP \rightarrow PP \rightarrow PP$

Command		Function	Description
1 6	NC	CLOSING/OPEN- ING SAFETY DEVICE	For safety devices with self-test input: When selecting $P \rightarrow S \parallel$ , connect the output contact of the safety device to terminals 1-6-8 on the control panel (in series with the photocell output contact, if installed). If $B \rightarrow S \parallel$ , $B \rightarrow S \parallel$ and $B \rightarrow S \parallel$ .
1 — <b>ww</b> — 6R	R= 8.2kΩ	OPENING RESISTIVE SAFETY EDGE	With $\Pi P \rightarrow GR$ selected, confirmed by the message $ND$ on the display, a short circuit or open circuit state of the resistance triggers arrest with disengagement and reverses the direction of the automation in accordance with the value set for the parameter $GR$ .
1 — <b>ww</b> — 8R	R= 8.2kΩ	CLOSING RESISTIVE SAFETY EDGE	With $\Pi P \rightarrow \Pi R$ selected, confirmed by the message $N \square$ on the display, a short circuit or open circuit state of the resistance triggers arrest with disengagement and reverses the direction of the automation in accordance with the value set for the parameter $\Pi R$ .

# 5.3 Limit switch inputs

Command		Function	Description
0 — 11A	NC	OPENING LIMIT SWITCH M1	Extra low voltage limit switch logic contact. Its behaviour depends on the value set in parameter ${\bf F}{\bf H}.$
0 — 12A	NC	CLOSING LIMIT SWITCH M1	Extra low voltage limit switch logic contact. Its behaviour depends on the value set in parameter $F\ H.$
0	NC	OPENING LIMIT SWITCH M2	Extra low voltage limit switch logic contact. Its behaviour depends on the value set in parameter $\digamma$ $\Box$ .
0 — 12B	NC	CLOSING LIMIT SWITCH M2	Extra low voltage limit switch logic contact. Its behaviour depends on the value set in parameter $\digamma$ $\Box$ .

# 6. Outputs and accessories

Output	Value of accessories	Description
<b>⊗ ⊗</b> 24V-	24V~ 0.3A max	AC power supply to accessories Output for power supply to external accessories.
- + + 0 1	24V <del></del> 0.3A max	Accessories power supply Output for DC power supply to external accessories.
3W max 24V == 0.3A max		Automation status lamp (configurable) For the operating mode of output 30-13, refer to the selection <a href="#">∄用→ 13</a> . <a href="#">IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII</a>
3W max  S 3 13 30 2 3 4 9	24V <del></del> 0.3A max	Configurable 24V $=$ output For the operating mode of output 30-G3, refer to the selection $\blacksquare \Pi \to \blacksquare \exists$ . The total sum of the current values delivered from the 24V-outputs 1 and
AUX 1 AUX 2	GOPAVRS LAB9 BIXR2 BIXPR2 BIXLR42 LAN7S	The control panel has two slots for plug-in command and safety boards. The action of the control board can be selected using \$\frac{1}{2} \cdot \text{PM}\$ for AUX1 and \$\frac{1}{2} \cdot \text{PN}\$ for AUX2. When using slot-in radio boards, remove the RDX module. The display will show \$\frac{1}{2}'\$.  **WARNING: the plug-in cards must be inserted and removed with the power supply disconnected.  **NOTE: the current absorption of the accessories installed in the slots AUX1/AUX2 if associated with output 1" by the relative jumper, must be considered in the total current deliverable by output 1 [0.3A]. Differently if associated to "30" must be considered in the calculation of the total current deliverable by output 30 [0.3A].



Output	Value of accessories	Description	
	ANTENNA	Input for GOL148REA external antenna or rigid wire antenna supplied according to the operating frequency of the receiver module used.	
	230V~ 25W max	230V <b>flashing light</b> For connection of a <u>230 V~ flashing light</u> with auto-flashing function.	
LK~	12V ~/15W 0.3A max (max 3s)	<b>Electric lock</b> It is activated when the operation begins with the automation closed. To modify the operating mode of the LK output, refer to the selection $\  \  \  \  \  \  \  \  \  \  \  \  \ $	
	12V~/0.1A (continuous)	WARNING: a short circuit in the electric lock causes fuse F2 to blow.	
RDX	ZENRS ZENPRS (optional)	For installation of a ZENRS (433.92 MHz) or ZENPRS (868.35 MHz) type radio receiver module, purchasable separately. Operation is enabled by selecting $\mathbb{F} \cap \mathbb{F} \cap \mathbb{F}$ . When using slot-in radio boards, remove the RDX module. The display will show $\mathbb{F} V$ . WARNING: the modules must be inserted and removed with the power supply disconnected.	
СОМ	M BIXMR2	<b>COM</b> - Enables saving of operating configurations with function $\Gamma \to \Gamma$ . Saved configurations can be recalled with function $\Gamma \to \Gamma$ . The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel.	
		<b>WARNING</b> : the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction.	
SCI	FUTURE USE		

# 7. Jumper setting

Jumper	Description	OFF •	ON
JR1	Display mode selection	<b>Display mode</b> The values and parameters present can be only displayed.	Maintenance mode Maintenance mode. The values and parameters present can be displayed and modified. Activated maintenance mode is indicated by the permanent lit on of the right- hand point on the display.
Jumper	Description	30 1	30 1
AUX1	Selection of power supply - auxiliary board 1	AUX1 powered from 0-1	AUX1 powered from 0-30 (default setting)
AUX2	Selection of power supply - auxiliary board 2	AUX2 powered from 0-1	AUX2 powered from 0-30 (default setting)



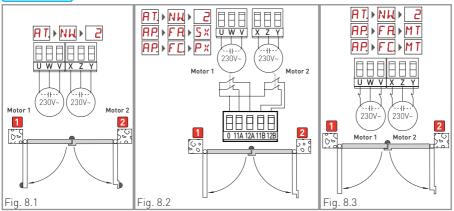
# 8. Application examples

**WARNING**: make sure that the operating forces of the gate wings comply with the EN12453 standard.

# 8.1 Automations with two swinging gates



When the Ditec LCA80 control panel is used in applications for automations with two overlapping swinging gate wings, the following connections may be made:



(Fig. 8.1) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.

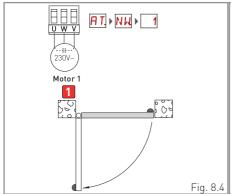
(Fig. 8.2) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closing).

(Fig. 8.3) Installation with the use of electric limit switches for opening and closure, series connected to the motor's phases.

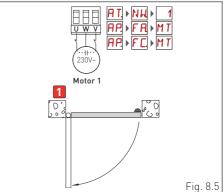
# 8.2 Automations with one swinging gate wing



When the Ditec LCA80 control panel is used in applications for automations with one swinging gate wing, the following connections may be made:



(Fig. 8.4) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.



(Fig. 8.5) Installation with a mechanical end stop for closure and the use of electric limit switches for opening and closure, series connected to the motor's phases.

# 9. Using menus

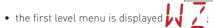


**NOTE**: pressure on the keys may be quick (less than 2s) or prolonged (longer than 2s). Unless specified otherwise, quick pressure is intended. To confirm the setting of a parameter, prolonged pressing is necessary.

## 9.1 Switching the display ON and OFF

The procedure to switch on the display is as follows: ENTER

- press the key
- the display functioning check starts



The procedure to switch off the display is as follows:

• press the key

NOTE: the display switches off automatically after 60 s of inactivity.

# 9.2 Navigation keys

- UP and DOWN keys: for scrolling through level one or two menus and through the list of possible values for a specific parameter.
- ENTER key: accesses the next menu level or the list of possible values for a menu parameter. Press and hold to confirm selection of the currently displayed parameter value.
- ESC key: go back to previous step in navigation.
- Simultaneous pressing of the keys **UP** and **ENTER** performs an opening command.



• Simultaneous pressing of the keys **DOWN** and **ENTER** performs a closing command.

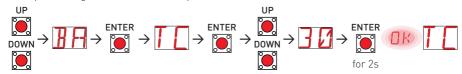


• <u>Simultaneous</u> pressing of the keys **UP** and **DOWN** performs a POWER RESET command. (interruption of the power supply and restart of the automation).

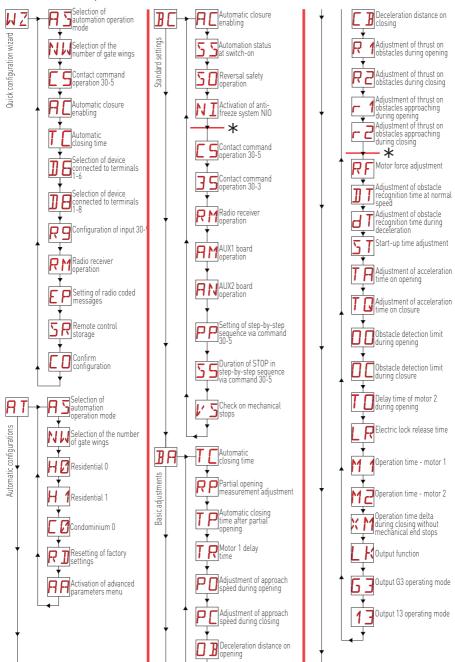


- Hold down the **UP** or **DOWN** key to begin fast menu scrolling.
- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.

Example: setting of 30 seconds for TC parameter.

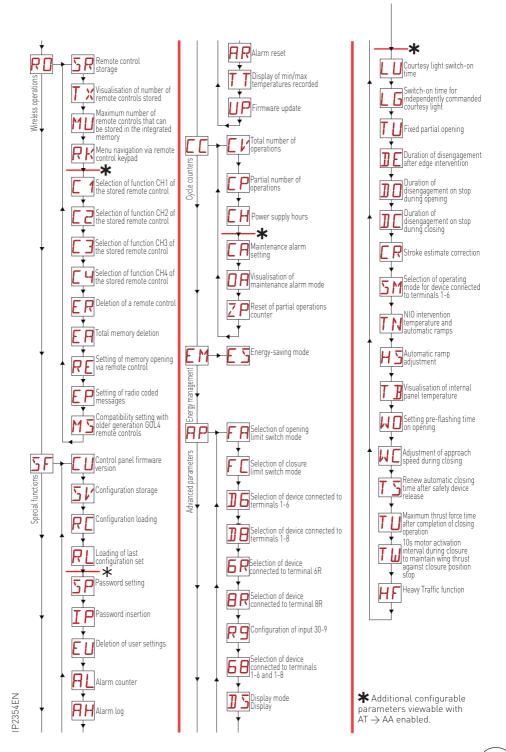


# 9.3 Menu map



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# 10. Setting up product for first use

Use the WIZARD (WZ) wizard or the level two AT menu (automatic configuration) to set the product up rapidly with a guick configuration procedure [see parag. 11.2].











# 10.1 WZ configuration wizard menu

#### To access the WZ quick configuration wizard menu:

Hold down the ENTER button for 2 seconds.

Once the message OK stops flashing, the first menu parameter:





 $\mathbb{N} \nearrow \mathbb{N}$  is displayed for 2 sec.  $\mathbb{N} \nearrow \mathbb{N}$ 





#### To set a parameter:

- 1. Press ENTER to access the configuration items.
- 2. Scroll UP/DOWN the possible options.
- 3. To confirm, press the ENTER button for 2 seconds. The selected value flashes and when it has finished, the next parameter appears.





Display







· AS - Motor operating mode







#### List of parameters in WIZARD menu:

# WZ - Quick configuration wizard

## Description

#### • 00. Automatic operation with deceleration (default)

Recommended use: for electromechanical motors installed on gates with unimpeded movement throughout entire stroke, and which use mechanical stops to determine the opening and closing strokes for every operation.

- · Mechanical stop check function.
- · Deceleration control.
- · Obstacle detection with reversal
- Force set at maximum value possible.

#### • 01. Automatic operation without deceleration

Recommended use: for electromechanical motors installed on gates with impeded movement in proximity of outermost opening and closing positions, and which use mechanical stops to determine the opening and closing strokes for every operation.

- · Mechanical stop check function.
- Constant speed throughout entire stroke.
- Obstacle detection with reversal.
- Force set at maximum value possible.

#### • 02. Timed operation with deceleration

Recommended use: for electromechanical or hydraulic motors installed on gates with unimpeded movement throughout entire stroke, and which do not provide for mechanical stops on opening except as an emergency measure in case of overrun.

- Features:
- Timed stroke based on M1 and M2 values.
- Deceleration control.
- · Obstacle detection with reversal.
- Force set at maximum value possible.



#### • 03. Timed operation without deceleration Recommended use: for electromechar

Recommended use: for electromechanical or hydraulic motors installed on gates with impeded movement in proximity of outermost opening and closing positions, and which do not provide for mechanical stops on opening except as an emergency measure in case of overrun.

#### Features:

- Timed stroke based on M1 and M2 values.
- Constant speed throughout entire stroke.
- Obstacle detection with reversal.
- · Force set at maximum value possible.

#### 04. Timed operation with force limiting

Recommended use: for electromechanical or hydraulic motors installed on particularly problematic gates with impeded movement throughout entire stroke, and which do not provide for mechanical stops on opening except as an emergency measure in case of overrun.

#### Features:

- Timed stroke based on M1 and M2 values.
- · Constant speed throughout entire stroke.
- · Obstacle detection disabled.
- Reduced force value.



**WARNING**: this operating mode may only be set if the gate is fitted with self-monitoring safety sensing edges as the obstacle recognition function is disabled.

#### NW - Number of wings.

- 1: single wing
- 2: two wings
- C5 Operation of command associated with contact 30-5
- 1-5: step-by-step (default)
- 1-3: opening
- **NO**: none

#### AC - Enabling of automatic closure

- ON: enabled (default)
- **OF**: disabled

#### TC - Setting of automatic closing time [seconds]

[NOTE: only viewable visible if AC = ON was selected in previous step]

- from 0" to 59" with intervals of 1 second.
- - from 1' (default) to 2' with intervals of 10 seconds.

# חר

**Duick configuration wizard** 

#### D6 - Selection of device connected to terminals 1-6

#### • NO: none

• PH: photocells (default)

For other options, see the specific menu.



# D8 - Selection of device connected to terminals 1-8 • N0: none

• PH: photocells (default)

For other options, see the specific menu.



#### RM - Radio receiver operation

- 1-3: step-by-step
- 1-5: opening (default)



#### EP - AES (Encrypted Packet) reception setting

If the possibility to receive coded messages is enabled, the control panel will be compatible with remote controls of the "ENCRYPTED" type.

- ON: enabled
- OF: disabled (default)

# SR - Remote control storage

When you press ENTER, SR starts to flash and you can associate the desired buttons.

Once OK is displayed, SR starts to flash again and you can associate the next button. To quit, press ESC or ENTER for 2 seconds and go on to the next item.

NB: if NO flashes on the display, the remote control may already be stored.

#### CO - Save Wizard settings

Here you can save the parameters that have previously been set.

• YS: to save and perform a card RESET

• NO: to quit without saving and go back to a blank screen (central part only)

NOTE: the message CO and YS/NO sub-menus flash constantly.

#### To save the configuration:

In the CO parameter select YS (yes) and press the ENTER button for 2 seconds.

After saving, a board POWER RESET cycle is performed automatically:







#### To guit without saving changes:

Select the option NO for the parameter CO and then press and hold ENTER for 2 seconds ENTER

ENTER





Or: from any main parameter, press the ESC button for 2 seconds. Example:







- The set values are only stored on the card if they are saved using the CO parameter.
- The parameter CO and the YS/NO options flash constantly.
- After confirming a configuration parameter, the wizard moves on automatically to the next parameter.
- The UP/DOWN buttons may be used at any time, however, to scroll through parameters.
- There is no time limit for selecting and the wizard will not guit automatically.

# 10.2 Basic example of start-up



NOTE: although this procedure applies to the "Automatic mode with deceleration" (FT  $\rightarrow$  H = 20, it also serves as a quide for the other modes



WARNING: the system must have sufficiently robust mechanical end stops or stop limit switches must be installed.



WARNING: if the control panel is used to replace an identical control panel which is faulty, the last automation configuration can be reset by inserting the old control panel storage module into the new control panel and loading the last set configuration using the menu sequence  $\overline{SF} \rightarrow RL$ 



WARNING: before using the automation, make sure that the operating forces of the gate wings comply with the EN 12453:2017 standard and subsequent revisions.

- 1. Turn on the power
- 2. Activate the WZ configuration wizard menu. Set the selections required for the system to be developed.
- 3. Make a jumper for the safety contacts 1-6, 1-8 and 1-9. If not deactivated via the menu param- $|AP| \rightarrow |B|$  and  $|AP| \rightarrow |RS|$
- 4. With the automation idle in the intermediate position, give an opening command (ENTER + UP keys).
  - Check that the gate wings move in the correct direction. If the direction is not correct, invert the motor phase connections (U-V or X-Y) and repeat the procedure described above. Check that the automation reaches the gate open position and stops against the corresponding mechanical end stops (learning operation).
- 5. Give a closing command (ENTER + DOWN keys) or wait for the automatic closure to intervene if activated and check that the automation performs the corresponding operation by stopping on the mechanical closing end stops (learning operation).
- 6. Connect the safety devices after removing the jumpers 1-6, 1-8 and 1-9, or reactivating the corresponding inputs using the menu parameters  $AP \rightarrow BB | AP \rightarrow BB |$  and  $AB \rightarrow BB | AP \rightarrow BB |$ Make sure the various safety devices are operating correctly.





NOTE: the first closing operation after a power cut or during the learning procedure is carried out with one gate wing at a time.

## 10.3 Frequently used menu sequences

## 10.3.1 Enabling the configurations

Step-by-step mode without automatic closure (residential use)



#### 10.3.2 Adding remote controls



## 10.3.3 Configuring the NC contact safety devices

Example 1 - Configuring the photocells connected to terminals 1-8 and 1-6 [standard settings]



Example 2 - Configuring the safety edge with safety test simultaneously connected to terminals 1-6 and 1-8

$$\begin{array}{c} \text{DOWN} \\ \text{DOWN} \\ \text{OP} \end{array} \rightarrow \begin{array}{c} \text{ENTER} \\ \text{OP} \end{array} \rightarrow \begin{array}{c} \text{$$

## 10.3.4 Configuring the resistive safety edges

Example 1 - Configuring the resistive safety edges connected to terminals 1-6R and 1-8R



## 10.3.5 Configuring the limit switches

Example 1 - No limit switch. Gate wing stops against mechanical end stops (standard setting)

$$\begin{array}{c|c} \text{Set} \\ \text{UP} \\ \text{OWN} \\ \text{OP} \\ \text{O$$

Example 2 - Stop limit switch. Gate wing stops against limit switches connected to terminals 11A/B and 12A/B

With these settings, if an obstacle is detected while opening, the gate wing stops and performs a disengagement operation whereas during a closing operation, the gate wing reopens.

Example 3 - Example of mixed configuration. Gate wing stops against mechanical closing end stops and opening limit switches and reverses motion if an obstacle is detected. The limit switches must be connected to terminals 11A/B and 12A/B. Set



With these settings, the gate wing stops against its respective mechanical closing end stop and the opening limit switch. If an obstacle is detected during the opening and before the activation of the stop limit switch, the gate wing stops with a disengagement operation. If an obstacle is detected during closing and before the activation of the proximity limit switch, the gate wing reopens; once the proximity limit switch has been activated, the gate wing stops against the obstacle.

# 11. Configuration and settings menu



**NOTE**: depending on the type of automation and control panel, some menus may not be available.

#### 11.1 Main menu

Display	Description		
WZ	WZ - Quick configuration wizard Quick configuration menu		
AT	AT - Automatic Configuration The menu allows you to manage the automatic configurations of the control panel.		
BC	BC - Basic Configuration The menu allows you to display and modify the main settings of the control panel.		
ŢД	BA - Basic Adjustments The menu allows you to display and modify the main adjustments of the control panel.		
ווע	NOTE: some settings require at least three operations before they are set correctly.		
RO	RO - Radio Operations The menu is used to manage the radio functions of the control panel.		
5F	<b>SF - Special Functions</b> The menu allows you to set the password and manage the special functions in the control panel (alarm management, diagnostics enabling, FW updating).		
	<b>CC - Cycle Counter</b> The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions.		
EM	<b>EM - Energy Management</b> This menu may be used to view and modify energy saving settings and adjustments (Green Mode).		
RP	<b>AP - Advanced Parameters</b> The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.).		
	NOTE: some settings require at least three operations before they are set correctly.		

From the main menu you can access the second level menu as follows:

- use the and keys to select the required function;
- press to confirm.

After confirming the selection, you access the second level menu.



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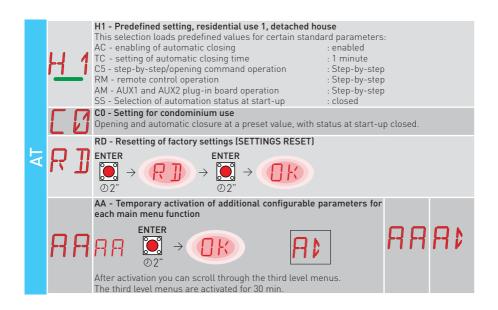
For each function of the main menu, there are also additional configurations that can be viewed by enabling the  $\bigcap$  function (see the following paragraph). The factory settings for the various second level menu parameters are underlined in green.



**NOTE**: to check if the parameters have actually been modified, quit the relative parameter and then access it again. The modifications will take effect from the next operation.

# 11.2 Level two menu - AT (Automatic Configuration)

	Display		Description									tions	
	,	AS - Mo									avail	able	
AT - Automatic configuration	A 2	AS - Motor operating mode  0. Automatic with deceleration				1 ]							
1.0		Value	Standard	P0	PC	ОВ	СВ	VS	R1	R2	r1	r2	RF
<b>1</b> 5		0	Automatic with deceleration	13	13	10	10	ON	10	10	15	15	99
		1	<u>Automatic without deceleration</u>	25	25	5	5	ON	10	10	10	10	99
		2	<u>Timed with deceleration</u>	13	13	10	10	OFF	10	10	15	15	99
		3	Timed without deceleration	25	25	5	5	OFF	10	10	10	10	99
		4	Timed with force limiting	25	25	5	5	OFF	99	99	99	99	50
	NN	NW - So In the c	election of the number of gate wi ase of automations with a single of	<b>ngs</b> gate v	wing,	conn	ect m	notor '	1.		1		2
	HØ	H0 - Predefined setting, residential use 0, detached house This selection loads predefined values for certain standard parameters: AC - Enable automatic closure : disabled C5 - step-by-step/opening command operation RM - remote control operation : Step-by-step AM - AUX1 and AUX2 plug-in board operation SS - Selection of automation status at start-up : open						)					



# 11.3 Level two BC menu (Basic settings)

	Display	Description	Sele	ctions avail	lable	
Basic settings	AC	AC - Enabling of automatic closure OF - Disabled ON - Enabled 1-2 - Dependent on input 30-2	0F		-	2
	55	SS - Selection of automation status at start-up OP - Open CL - Closed Indicates how the control panel considers the automation a of switch-on, or after a POWER RESET command.	at the time	0P		L
	50	SO - Enabling of reversal safety contact functioning during ON - Enabled OF - Disabled When enabled (ON) with the automation idle, if the contact ations are prevented. When disabled (OF) with the automation idle, if the contact operations are permitted.	1-8 is oper			N F
S C		NI - Enabling of NIO electronic anti-freeze system ON - Enabled OF - Disabled When enabled (ON), it maintains the efficiency of the motor temperatures.	r even at lo	w ambient	Ω	N
	ΝI	NOTE: for correct operation, the control panel must be ambient temperature as the motors.  The intervention temperature for the NIO system can be set by WARNING: When the NIO system is in operation, the 230 output will remain activated. The NIO function cannot with limit switches series connected to the phases [F4]	y selecting <b>f</b> IVAC (LP) fla be used wh	P→TN.  ashing light len motors		F



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# 11.3.1 Additional configurable BC level parameters available with ☐ Ţ → ☐ ☐ enabled

	Display	Description	Selections available
	<b>C</b> 5	C5 - Step-by-step/opening operation via 1-5 command (wakeup from stand-by) 1-3 - Opening 1-5 - Step-by-step L6 - Courtesy light command NO - Input 5 disabled	1-31 <u>-5</u> NOLG
S	35	35 - Operation of command associated with contact 1-3 1-3 - Opening 1-5 - Step-by-step LG - Courtesy light command NO - Input 3 disabled	1-31-5 NO LG
ng	RM	RM - Radio receiver operation 1-3 - Opening 1-5 - Step-by-step	1-31-5
Basic setti	ЯM	AM - Step-by-step/opening operation via command from AUX1 board 1-3 - Opening 1-5 - Step-by-step NO - Disabled	1-31 <u>-5</u> NO
BC - Ba	AN	AM - Step-by-step/opening operation via command from AUX2 board 1-3 - Opening 1-5 - Step-by-step NO - Disabled	1-31 <u>-5</u>
	РP	PP - Setting of step-by-step sequence via command 30-5 ON - Opening-Stop-Closing-Stop-Opening OF - Opening-Stop-Closing-Opening	ONOF
	55	<ul> <li>S5 - Duration of STOP in step-by-step sequence via command 30-5</li> <li>ON - Permanent (automatic closure is excluded until a new command is given)</li> <li>OF - Temporary (the automatic closure timer intervenes, if enabled)</li> </ul>	ONOF
	V 5	VS - Checking of mechanical end stops When enabled (ON), with every power supply connection, the automation automatically checks the mechanical opening and closing end stops/ stop limit switches. During the learning operation, the display shows the message Mand the closing operation involves one gate wing at a time (10).	<u>ON</u> OF

# 11.4 Level two BA menu (Basic adjustments)

NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

	Display	Description	Selections available
BA	T (-	TC - Setting of automatic closing time [s] It is set with different intervals of sensitivity. from 0" to 59" with intervals of 1 second; from 1' to 2' with intervals of 10 seconds.	0 0,5 9 1 , 2 ,





	Dis	play	Description		elections available	
	R	P	RP - Adjustment of partial opening measurement [%] Adjusts the percentage of operation in relation to the total opening of the automation. Partial opening is performed on gate wing 1. 10 - Minimum 99 - Maximum	16	<b>3</b> -50	3
	T	P	TP - Setting of automatic closing time after partial opening [s] It is set with different intervals of sensitivity. from 0" to 59" with intervals of 1 second; from 1" to 2" with intervals of 10 seconds.		30"	9
	T	R	TR - Motor delay time [s] Delay time for closure of gate wing 1 in relation to gate wing 2. 00 - 30s			
ents	p		PO - Adjustment of approach speed during opening Indicates the speed from the end of the deceleration ramp to the end of the opening stroke 10 - Minimum 25 - Maximum	11	<b>13</b>	- כ
Basic adjustments	p		PC - Adjustment of approach speed during closing Indicates the speed from the end of the deceleration ramp to the end of the closing stroke. 10 - Minimum 25 - Maximum	16	13	5
		3	OB - Setting of deceleration/braking time during opening [s] Indicates the time between the start of the deceleration ramp and the end of the opening stroke 1 - Minimum 30 - Maximum		19	
- BA		3	OB - Setting of deceleration/braking time during closing [s] Indicates the time between the start of the deceleration ramp and the end of the opening stroke 1 - Minimum 30 - Maximum		10	
	R	1	R1 - Adjustment of thrust on obstacles during normal operation at constant speed for both motors when opening. [%]  The control panel is fitted with a safety device which, when it detects an obstacle:  - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with ♠P→ 测€;  - reverses the movement during closure operations outside the limit area for detecting obstacles;  - stops the movement during closure operations within the limit area for detecting obstacles.  The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined according to the selections 测升→ ① and 测升→ ①:  O - Minimum thrust  NB: if set to 99%, obstacle detection is disabled during opening.		<b>1</b> 0	9



	Display	Description	Selections available
BA - Basic adjustments	R 2	R2 - Adjustment of thrust on obstacles during end position approach phase normal movement at constant speed for both motors when closing. [%]  The control panel is fitted with a safety device which, when it detects an obstacle:  - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with PP→ JE;  - reverses the movement during closure operations outside the limit area for detecting obstacles;  - stops the movement during closure operations within the limit area for detecting obstacles.  The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined according to the selections JP→ DD and JP→ DD:  O - Minimum thrust  NB: if set to 99%, obstacle detection is disabled during closing.	avaitable
	r- 1	r1 - Adjustment of thrust on obstacles during end position approach phase at constant speed for both motors when opening. [%] The control panel is fitted with a safety device which, when it detects an obstacle: - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with ЯР→ №: - reverses the movement during closure operations outside the limit area for detecting obstacles; - stops the movement during closure operations within the limit area for detecting obstacles.  The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined according to the selections    NB: if set to 99%, obstacle detection is disabled during opening.	0 0·9 9 15
	r- 2	r2 - Adjustment of thrust on obstacles approaching at constant speed for both motors when closing. [%]  The control panel is fitted with a safety device which, when it detects an obstacle: - stops the opening movement and, if beyond the limit for obstacle detection, performs a disengagement operation, the duration of which is settable with ЯР→ ]] €: - reverses the movement during closure operations beyond limit for obstacle detection; - stops the movement during closure operations within limit for obstacle detection. The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined on the basis of selections [] ↑ ○ ○ and [] ↑ ○ ○ .  Minimum thrust  NB: if set to 99%, obstacle detection is disabled during closing.	<b>15</b>





# 11.4.1 Additional BA level parameters that can be configured (available with $\Pi$ $T \to \Pi \Pi$ enabled)

NOTE: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

	Display	Description	Selections available
	RF	RF - Motor force adjustment. [%] Enabled only during operations in which sensitivity R1, R2, r1 or r2 is set to 99%	20,99
	IJΤ	DT - Adjustment of obstacle recognition time at normal speed. [s/100] 20 - Minimum 99 - Maximum	20,99
	dТ	dT - Adjustment of obstacle recognition time during deceleration. [s/100] 20 - Minimum 99 - Maximum	<u> </u>
ments	5 T	ST - Adjustment of start time [s] During start-up, obstacle detection is disabled. 2.0 - Minimum 3.0 - Maximum	2.0,3.0
Basic adjustments	TA	TA - Adjustment of acceleration time during opening [s] 0.5 - Minimum 1.5 - Maximum	Ø.5, 1.5
1	TQ	TQ - Adjustment of acceleration time during closing [s] 0.5 - Minimum 1.5 - Maximum	Ø.5, 1.5
BA	00	OO - Obstacle detection limit during opening [%] Indicates the percentage of the distance travelled during ∃ A → ○ ∃ in which disengagement is deactivated.  NOTE: not active if AP→FA→5 x or if AP→FA→P x.	05,99
		OC - Obstacle detection limit during closing [%] Indicates the percentage of the distance travelled during  ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	05,99
	T	TO - Setting motor 2 opening delay time [s] Adjustment, in seconds, of the delay time for starting the operation of motor 2, in relation to motor 1.	03/30
	LR	LR - Electric lock release time [s] If enabled, this indicates the electric lock activation time at the start of every opening operation with the automation closed.	0.5,2.5



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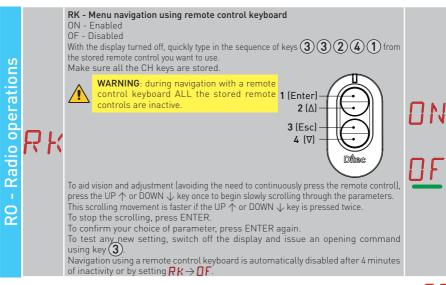
	Display	Description	Selections available	
ts	11 1	M1 - Operation time - motor 1 [s] Adjustment, in seconds, of the total operation time for motor 1. 02 - Minimum 99 - Maximum  WARNING: it is set with a sensitivity interval of 0.5s, shown when the decimal point on the right lights up.  Example:	<b>0</b> 2,99	
	M2	M2 - Operation time - motor 2 [s] Adjustment, in seconds, of the total operation time for motor 2. 02 - Minimum 99 - Maximum  WARNING: it is set with a sensitivity interval of 0.5s, shown when the decimal point on the right lights up.  Example: ☐ ☐ = 7 seconds / ☐ ☐ = 7.5 seconds  NOTE: the setting of M2 is only active with ☐ → V 5 → ☐ F.	0 2,9 9	
ustmer	×Μ	XM - Variation in time during closing without mechanical end stops. [s] Variation in time to be added to M1 and M2 during closing. 00 - Minimum 30 - Maximum		
BA - Basic adjustments	ΧT	XT - Variation in operation time when reversing. [s] Variation in time to be added to OB and CB. 00 - Minimum 30 - Maximum		
	LK	LK - LK output operating mode~  00 - Courtesy light  01 - Activation of electric lock  02 - Activation of electric lock with release stroke  03 - Output activated with gate closed (for fail-safe electromagnets)  04 - Output activated with gate open  05 - Output activated with gate moving (can be used for electromagn powered throughout opening or closing operations)  06 - Output activated during opening  07 - Output activated during closing  08 - Maintenance alarm  0N - Output always active	ets which need to be	
	<b>6</b> 3	ON - Output always active  G3 - G3 output operating mode  00 - Courtesy light 01 - ON-OFF flashing light 02 - Permanent flashing light (auto-flashing) 03 - Proportional indicator light for open gate (quick flashing when opening, permanently of gate open, slow flashing when closing)  Of - Indicator light for open gate (it comes on when opening starts and remains on until or		

ts	Display	Description	Selections available
BA - Basic adjustments	13	13 - 13 output operating mode 00 - Courtesy Light 01 - ON-OFF flashing Light 02 - Permanent flashing Light (auto-flashing) 03 - Proportional indicator Light for open gate (quick flashing when opening gate open, slow flashing when closing) 04 - Indicator Light for open gate (it comes on when opening starts and rehas been completed) 05 - Gate stationary and closed indicator Light 06 - Gate stationary and fully open indicator Light 07 - Gate moving indicator Light (on both during opening and closing) 08 - Gate closing indicator Light 10 - Maintenance alarm 0N - Output always active	

# 11.5 Level two RO menu (Radio operations)

		titwo ito inicina (itaaio operationo)					
	Display	Description					
Radio operations	SR - Remote control storage You can directly access the Remote control storage menu even with the display tu only with the Display visualisation mode option set to 00 or 03: - for transmitting a remote control not present in the memory; - for transmitting an unstored channel of a remote control already present in the memory.  ENTER  ENTER  O2"  WARNING: if the display shows ND flashing, the remote control may stored.						
	Τx	TX - Visualisation of counter showing remote controls stored  ENTER  The property of the control					
R0 - R	МЦ	MU - Indication of maximum number of remote controls that can be stored in the integrated memory  You can store a maximum of 100 or 200 remote control codes.  ENTER  ENTER  2" 10 - 100 remote controls that can be stored 20 - 200 remote controls that can be stored  WARNING: selecting MU -> 2 (200 remote controls), the configurations U 1 and U 2 saved with the 5F -> 51 command will be lost. This also applies for the last configuration reloaded with RL. In addition, new configurations cannot be saved on U 1 and U 2.					





# 11.5.1 Additional configurable BO level parameters available with ☐ Ţ → ☐ ☐ enabled

		, , ,	elections
	Display	Description	available
- Radio operations	[ 1 [ 2 [ 3 [ 4	C1, C2, C3, C4 - Selection of CH1, CH2, CH3, CH4 function of stored remote control  NO - No setting selected  1-3 - Opening command  1-4 - Closing command  1-5 - Step-by-step command  P3 - Partial opening command  L6 - Command to switch the courtesy light on/off  1-9 - STOP command  If even just one [any] CH key of the remote control is stored, the opening or step-by-step command is implemented.  NOTE: the [-3] [opening] and [-5] [step-by-step] options are available as alternatives, and depend on the selection [-3] PM.  If 2-4 CH keys of a single remote control are stored, the functions matched in the factory with the CH keys are as follows:  CH1 = opening/step-by-step command; [-3] [-5] [depending on parameter PM]:  CH2 = partial opening command; [-3] [-5]  CH3 = command to switch on/off the courtesy light; [-5]	
80		ER - Deletion of a single remote control	
	ER	ENTER  O 2"  P P P P P P P P P P P P P P P P P P P	
		EA - Total deletion of part of storage used for remote controls	
	EΑ	$ \begin{array}{c} \text{ENTER} \\ \bigcirc \bigcirc$	

# 11.6 Second level menu - SF (Special Functions)

	Display	Description	
	СШ	CU - Displaying the control panel firmware version ENTER $\rightarrow$ $\rightarrow$ 1. 1 $\rightarrow$ Release 1.1 [example]	
		or burning above coming a data of control of participation and all of the control	Selections available
ns	54		L 1
unction	J /	By selecting $\mathbb{R} \bigcirc \to \mathbb{M} \cup \to 10$ you can save up to 2 personalised configurations in memory positions $\cup$ 1 and $\cup$ 2 only with the storage module present on the control panel.	<u>U</u> 2
al fi		WARNING: if $\mathbb{R}$ $\longrightarrow$ $\mathbb{N}$ $\longrightarrow$ $\mathbb{N}$ is selected, no user configuration can be saved on $\mathbb{N}$ 1 and $\mathbb{N}$ 2.	
SF - Special functions	RC	RC - Configuration loading ENTER $\rightarrow$ $\square$ $1 \rightarrow \square$ $1 \rightarrow$	<b>∐</b> 1
SF		You can load the previously stored user configurations [ ] and [ ] on the memory module of the control panel.	U2
	R!	RL - Loading of last configuration set ENTER $\Rightarrow$	
	r L	the control panel automatically saves the last configuration set, and keeps it me the storage module. In the event of a fault or the replacement of the control par configuration of the automation can be restored by inserting the storage module the last configuration set.	nel, the last



# 11.6.1 Additional configurable SF level parameters available with $\sqcap$ $\intercal$ $\rightarrow$ $\sqcap$ $\sqcap$ enabled

	Description							
	5	b	SP - Setting the password ENTER  UP DOWN  [example] $\bigcirc 2$ "  NOTE: this can only be selected when the password is not set.  Setting the password prevents unauthorised personnel from accessing selections and adjustments. You can delete the set password by selecting the sequence JR1=0N, JR1=0FF, JR1=0N.					
	Ι	P	IP - Inserting the password  ENTER  UP  DOWN  [example]  DOWN  [example]  DOWN  ENTER  DOWN  [example]  DOWN  FINTER  FINTER  FINTER  DOWN  FINTER  FINTER					
S			EU - Deletion of user configurations and last configuration set (can be called up from RL)					
Special functions	Ε	U	ENTER  ENTER  O 2"  ENTER  O 2"					
ecial f	R	L	AL - Alarm counter Used to view, in sequence, the counters of alarms that have been triggered at least once (alarm code + number of times triggered). With UP and DOWN, you can scroll through all the counters and see all the alarms recorded.					
SF-Sp	R	AH - Alarm log Used to view, in sequence, alarms that have been triggered (up to a maximum of 20). With UP and DOWN, you can scroll through the entire alarm log. The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number [0] sponds to the oldest alarm.						
	AR - Alarm reset Resets all the alarms in the memory (counters and log).  ENTER  O 2"  NOTE: when the installation has been completed, you are advised to delete the a in order to facilitate future checks.							
	T	T	TT - Display of min/max temperatures recorded - press for 2 sec to reset the values; - minimum value with active right decimal point.					
	L	P	UP - Firmware update Activates the card bootloader in order to update the firmware.  ENTER  2 2"					

# 11.7 Second level menu - CC (Cycles Counter)

	·						
က်	Display	Description					
counters		CV - Display of total operations counter  ENTER  →					
ycle c	C P	CP - Display of partial operations counter  ENTER  → 1 → 1 → 716 operations [example]					
0-00	[H	CH - Display of power supply hour counter  ENTER  Display Disp					

# 11.7.1 Additional configurable CC level parameters available with $\sqcap$ $\uparrow$ $\rightarrow$ $\sqcap$ enabled

	Display	Description	Selections available	
CC - Cycle counters	C A	CA - Setting the maintenance alarm  (factory setting - alarm deactivated: 0.0 00. 00)  You can set the required number of operations (regarding the partial operations counter) for signalling the maintenance alarm.  When the set number of operations is reached, the alarm message appears on the display   1/2 .  Example: Setting the maintenance alarm after 700 operations (00) (07) (00)  ENTER  OPPOWN  ENTER  OPPOWN  ENTER  OPPOWN  OPPOWN		
	0 A	OA - Selecting maintenance alarm display mode 00 - Visualisation on display (alarm message ✔ ② 01 - Visualisation on flashing light (with the automation idle, 4 flashes are made and then repeated every hour) and on display (alarm message ✔ ②). 02 - Visualisation on "open gate" indicator light (with the automation closed, 4 flashes are made and then repeated every hour) and on display (alarm message ✔ ②).		
5	Z P	ZP - Reset of partial operations counter ENTER  2" 2" For correct functioning, you are advised to reset the partial operations counter: - after maintenance work; - after setting the maintenance alarm interval.		

# 11.8 Level two EM menu (Energy management)

ent	<b>Display</b> Description				
<b>Energy management</b>		ES - "Green Mode" (energy-saving) (disconnection of accessories connected to terminals 0-1 when the automation is in standby)  ON - Enabled (the red point on the right of the display flashes every 5 s. Outputs ~LP-,~LK-, 30-13 and 30-G3 are not affected by the low-consumption mode).  OF - Disabled.			
	E 5	Power supply disconnection mode is activated after 15 s with the gate closed, or when the gate is idle and automatic closure is not enabled. The automation resumes normal operation when a command is received from the radio board [ZENRS-ZENPRS] or after a contact 30-5, 30-20, 30-3 or 30-4.	ΠF		
EM-		<b>WARNING:</b> if you use accessories that need to remain powered even with Green Mode enabled (e.g. LAN4 or GOPAV), set the jumper AUX1-2 relating to the slot used on power supply 0-30.	<u> </u>		

EN

11.9 Level two AP menu (Advanced parameters)

11.	9 L	eve	two AP menu (Advanced parameters)		
	Display		Description		ctions lable
AP - Advanced parameters	F	R	FA - Motor 1 and 2 opening limit switch mode NO: no limit switch (timed operation or with detection of stop) SX: stop limit switch PX: proximity limit switch (when activated, if an obstacle is detected, it is considered a stop) MT: stop limit switch series connected to the motor phase	NO PX	5× MT
	F		FC - Motor 1 and 2 closing limit switch mode NO: no limit switch (timed operation or with detection of stop) SX: stop limit switch FX: proximity limit switch (when activated, if an obstacle is detected, it is considered a stop) MT: stop limit switch series connected to the motor phase	NO Px	5× MT
	I	5	D6 - Selection of device connected to terminals 1-6 N0 - None SE - Safety sensing edge (if contact 1-6 opens, 10 cm disengagement is implemented after stop). S41 - Safety edge with safety test (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection	541 541	5E PH
	I	8	D8 - Selection of device connected to terminals 1-8 N0 - None SE - Safety edge S41 - Safety edge with safety test PH - Photocells P41 - Photocells with safety test	140 141 141 141 141	2E PH
	5	R	<ul> <li>6R - Device connected to terminal 6R</li> <li>NO - None</li> <li>01 - Stop with disengagement during both opening and closing operations.</li> <li>[Once the idle resistance value (8.2K) has been reset, operation is resumed].</li> <li>02 - During closure, a significant variation in the resistance value above or below the idle resistance value (8.2K) stops and reverses movement. When the automation is stationary, all operations are disabled.</li> </ul>	NO 0 1	02
	8	R	8R - Device connected to terminal 8R NO - None 01 - Stop with disengagement during both opening and closing operations. [Once the idle resistance value (8.2K) has been reset, operation is resumed]. 02 - During closure, a significant variation in the resistance value above or below the idle resistance value (8.2K) stops and reverses movement. When the automation is stationary, all operations are disabled.	NO 0 1	02
	R	9	R9 - Configuration of input 30-9 NO - Disabled 9P - Open state of an input triggers permanent stop. 9T - Open state of an input triggers temporary stop. Once contact closes, automatic closure time (if enabled) is activated. HR - Automation operates in "operator present" mode if input is open	ND 9P	9T HR
	5	8	68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8 NO - None SE - Safety edge S41 - Safety edge with safety test If different from NO, the simultaneous opening of inputs 1-6 and 1-8 causes: - movement stop and reversal during a closing operation movement stop and disengagement of a duration depending on the selection   P→ ■ during an opening operation.	N N	0 E 41

	Display	Description	Selections available
AP	115	DS - Setting of display visualisation mode without alarm 00 - No information displayed. 01 - Countdown to automatic closure displayed. 02 - Automation status (see paragraph 13.1). 03 - Commands and safety devices (see paragraph 13.2).  NOTE: the setting 1 allows you to see when a radio transmission is received, for range checks.	

11.9.1 Additional configurable AP level parameters available with  $\sqcap$   $\uparrow$   $\rightarrow$   $\sqcap$  enabled

**NOTE**: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

	Display	Description	Selections available
ers	LU	LU - Setting switch-on time for courtesy light (s) To enable this parameter, set at least one of the selections	NO 159 1', 2' 2', 3'
- Advanced parameters	L G	LG - Switch-on time for independently commanded courtesy light [s] To enable this parameter, set at least one of the selections	NO 159 1' - 2' 2' - 3' 0N
AP -	PT JE	PT - Fixed partial opening ON - Enabled OF - Disabled If ON, a partial opening command given on the partial opening position is ignored. With contact 30-20 closed (for example with the timer or manual selector), the gate will partially open. If it is then fully opened (command 30-3) and reclosed (even with automatic closing), it will stop at the partial opening position.  DE - Disengagement duration if an edge is triggered [s] Regulates the duration of the disengagement when an edge (active) is triggered during opening or closure. In the case of gates with two wings, it acts on both wings.	0 N <u>0 F</u>



	T	5	00,99	
	T	Ш	0.0,9.9	
АР	ТШ		TW - Thrust renewal time against closure position stop. 00 to 59 (minutes), 1h, 2h, 9h. This parameter may be used to hold the gate closed with motors which require thrust to be re-applied periodically to effectively hold the gate in a closed position (e.g. in case of pressure loss in hydraulic actuators when not in use). At each time interval set, the hydraulic unit delivers closing pressure to the motors for 10 seconds and activates the flashing lamp (is installed) to warn of the manoeuvre.  NOTE: Setting the parameter to 0.0 disables function.  WARNING: Check that the thrust deliverable by the motors is within the limits specified by the standard EN 12453:2017.	00°59 11°91
			Only use this function if effectively necessary.  HF - Heavy Traffic function ON - Enabled	
	H	lF	ON - Enabled OF - Disabled When this function is enabled, the automatic reclosing time is increased automatically to 3 min in the event of a series of consecutive operations due to frequent aperture requests (e.g. at peak traffic times in a condo-	ONOF
			minium application), to reduce wait times for users and to limit motor wear and the risk of overheating.	



# 12. Diagnostics

# 12.1 Data Logging integrated in the board

The Ditec LCA80 control panel is equipped with an internal system which allows the installer to check whether any alarms have been triggered, see how many times each alarm has been triggered and view a the log of the last twenty alarms.

#### 12.1.1 Alarm counter

With the third level menus enabled  $(AT \rightarrow AA)$ , go to  $AC \rightarrow AC$  to see all the alarms recorded by the control panel. The display alternately shows the alarm code and the number of times it was triggered.

Use the and keys to scroll through the entire list of alarm counters.

## 12.1.2 Alarm log

With the third level menus enabled  $(AT \rightarrow AA)$ , go to  $CF \rightarrow AA$  to see the alarm log (the last 20 alarms recorded). The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number corresponds to the oldest alarm.

Example: - 1 \_ [] ] \_ - 1 \_ [] ] \_ ....

UP DOWN

Use and to scroll through the alarm log.

# 13. Signals visualised on the display

- NOTE: depending on the type of automation and control panel, certain visualisations may not be available.
- 13.1 Display of automation status
- NOTE: the automation status display mode is only visible with Display visualisation mode set to 02.

AP > 15 > 02

Display	Description	Display	Description
	Automation closed	10	Automation opening
	Automation open	] 1	Automation closing, from partial opening
1 1	Automation stopped in intermediate position	1	Automation in partial opening
1	Automation closing		Automation partially open

# 13.2 Display of safety devices and commands

•	NOTE: the safety
	isation mode set

device and command display mode is only visible with Display visualat 01 or 03.

Display	Description	Display	Description
Display	1-2 - Automatic closure enable command.	Display	F.C Closure limit switch - motor 2
1- 2	2 Automatic closure chapte communit.	F.E.	1.0. Otosure timit switch motor 2
1-3	<b>1-3</b> - Opening command.	FA.	<b>FA.</b> - Opening limit switch - motor 1
1-4	<b>1-4</b> - Closure command.	F.A.	F.A Opening limit switch - motor 2
1-5	<b>1-5</b> - Step-by-step command.	5 1.	<b>S1.</b> - Stop detection during closure operation - motor 1.
1-6	<b>1-6</b> - Safety device with opening and closing stop.	5. 1.	<b>S.1.</b> - Stop detection during closure operation - motor 2.
1-8	<b>1-8</b> - Safety device with reversal during closing operation.	52.	<b>S2.</b> - Stop detection during aperture operation - motor 1.
1-9	<b>1-9</b> - STOP command.	5.2.	<b>S.2.</b> - Stop detection during aperture operation - motor 2.
5R	<b>1-6R</b> - Activation or malfunction of aperture operation stop resistive sensing edge		<b>00.</b> - Obstacle detection limit reached during aperture operation - motor 1.
BR	<b>1-8R</b> - Activation or malfunction of closure reversal resistive sensing edge	0.0.	<b>00.</b> - Obstacle detection limit reached during aperture operation - motor 2.
68	<b>68</b> - Device connected simultaneously to terminals 1-6 and 1-8.		<b>00.</b> - Obstacle detection limit reached during closure operation - motor 1.
P 3	P3 - Partial opening command.	O.C.	<b>00.</b> - Obstacle detection limit reached during closure operation - motor 2.
3P	<b>3P</b> - Opening command with operator present	RV	<b>RV</b> - Enable/disable built-in radio receiver via RDX.
46	<b>4P</b> - Closing command with operator present	MQ	<b>MQ</b> - Mechanical end stop learning operation in progress.
RX	<b>RX</b> - Radio reception (from any memorised key of a transmitter stored in memory)	HT	<b>HT</b> - Motor heating (NIO function) in progress.
NIV	NX - Radio reception (from any non-memorised key)	J 1	JR1 - Change in jumper JR1 status.
NX	<b>NOTE</b> : with the selection $PP \rightarrow PS \rightarrow PS \rightarrow PS$ 1, it is also visualised when a command is received from a non-stored transmitter.	PC	<b>PC</b> - Connected HOST (Personal Computer) recognised.
EX	<b>EX</b> - Rolling-code radio reception out of sequence	E 5	ES - Switch to Green Mode (energy-saving)
EP	<b>EP</b> - Radio reception not compliant with parameter configuration $\bigcirc \bigcirc \bigcirc$	1[	1C - Closing operation (1 gate wing at a time)
EX	CX - Command received from AUX1 board	L 6	LG - Courtesy light/garden light command
EY	CY - Command received from AUX2 board	HO	H0 - Pressure hold function activation for hydraulic pistons
FF	FC Closure limit switch - motor 1	H 5	<b>HS</b> - Activation of increased thrust force function in closure operation



# 13.3 Visualisation of alarms and faults



**WARNING**: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

Type of alarm	Display	Description	Operation	
	MB	<b>MB</b> - Motor 1 not detected during operation.	Check the motor 1 connection and if the thermal switch has tripped.	
	ME	MC - Motor 2 not detected during operation (if 2-motor operation is set).	Check the motor 2 connection and if the thermal switch has tripped.	
	IM	<b>MD</b> - Motor 1 aperture limit switch malfunction.	Check the connection of the motor 1 opening limit switch.	
	ME	<b>ME</b> - Motor 1 closure limit switch malfunction.	Check the connection of the motor 1 closing limit switch.	
	MF	<b>MF</b> - Motor 2 aperture limit switch malfunction.	Check the connection of the motor 2 opening limit switch	
	MG	<b>MG</b> - Motor 2 closure limit switch malfunction.	Check the connection of the motor 2 closing limit switch	
ıl alarm	MH	MH - Gate wing overlap incorrect	Check that the motor which is the first to make the opening [M1] is connected as shown in fig. 1.	
Mechanical alarm	MI	MI - Detection of fifth consecutive obstacle	Check for the presence of permanent obstacles along the stroke of the automation. Check the settings / operating of any limit switches.	
	ML	ML - Inverted motor 1 stop limit switches	Repair the motor 1 limit switch connection	
	1111	MM - Inverted motor 2 stop limit switches	Repair the motor 2 limit switch connection	
		<b>OD</b> - Obstacle on wing 1 detected during aperture.	Check for the presence of obstacles along the automation stroke.	
	OE	<b>OE</b> - Obstacle on wing 1 detected during closure.	Check for the presence of obstacles along the automation stroke.	
	OF	<b>OF</b> - Obstacle on wing 2 detected during aperture.	Check for the presence of obstacles along the automation stroke.	
	06	<b>OG</b> - Obstacle on wing 2 detected during closure.	Check for the presence of obstacles along the automation stroke.	
Settings alarm	56	<b>S6</b> - Incorrect setting of safety device test	Check the configuration of parameters ]6 . ]8.60 . If $60 \rightarrow 541$ , ]6 and ]8 cannot be $94$ or $541$ .	
Service	V O	<b>V0</b> - Maintenance request.	Proceed with the scheduled maintenance intervention.	

Type of alarm	Display	Description	Operation		
	I5	<b>I5</b> - No voltage 0-30 (faulty voltage regulator or short-circuit on accessories)	Check there is no short circuit in connection 0-30. If the problem persists, replace the control panel.		
	I 5	<b>16</b> - Excessive voltage 0-30 (faulty voltage regulator)			
	Ι٦	<b>17</b> - Internal parameter error - value outside limits	Reset. If the problem persists, replace the control panel.		
	I8	18 - Program sequence error	Reset. If the problem persists, replace the control panel.		
	IA	IA - Internal parameter error (EEPROM/FLASH)	Reset. If the problem persists, replace the control panel.		
alarm	IB	IB - Internal parameter error (RAM)	Reset. If the problem persists, replace the control panel.		
Internal control panel alarm	IC	IC - Operation time out error (>3 min).	Manually check that the gate wing moves freely. If the problem persists, replace the control panel.		
al contro	IE	IE - Power supply circuit fault	Reset. If the problem persists, replace the control panel.		
Interna	IM	IM - TRIAC alarm - motor 1 short circuited or always ON.	Reset. Check the settings / operating of any limit switches. If the problem persists, replace the control panel.		
	IN	<b>IN</b> - TRIAC alarm - motor 2 short circuited or always ON.	Reset. If the problem persists, replace the control panel.		
	ΙU	IU - Motor 1 voltage reading circuit test error.	Reset. If the problem persists, replace the control panel.		
	IV	$\ensuremath{\text{IV}}$ - Motor 2 voltage reading circuit test error.	Reset. If the problem persists, replace the control panel.		
	XX	XX - Firmware reset commanded by simultaneous usage + keys			
	NI	WD - Firmware reset not commanded			
Ę	RØ	RO - Storage module installed containing over 100 stored remote controls.  WARNING: the R□→M□→2□ setting is made automatically.	storage module, delete any stored remote		
Radio operations alarm	R3	R3 - Storage module not detected	Insert a storage module.		
	RH	R4 - Storage module not compatible with the control panel	Insert a compatible storage module.		
	RS	<b>R5</b> - No serial communication with the storage module	Replace the storage module.		
	R5	<b>R6</b> - Specific storage module for testing installed.			
Power supply alarm	P 1	P1 - Microcontroller voltage too low.	Check the control panel is powered correctly.		



Type of alarm	Display	Description	Operation
	A Ø	AO - Test of safety sensor on contact 6 failed.	Check the safety device is working properly.
			If the supplementary safety board is not inserted, check the safety test is disabled.
	<b>A</b> 1	A1 - Test of safety sensor connected simultaneously to contacts 6 and 8 failed.	Check the wiring and correct operation of the safety sensor.
	$\Box$	A3 - Test of safety sensor on contact 8 failed.	Check the safety device is working properly.
Accessories alarm	ל א		If the supplementary safety board is not inserted, check the safety test is disabled.
	<b>A5</b>	A5 - Test failed: safety sensor on contact 6R.	
	85	<b>A6</b> - Test failed: safety sensor on contact 8R.	
	A7	A7 - Incorrect connection of contact 9 to terminal 41	Check that terminal 41 and 9 are correctly connected.
	89	A9 - Overload on output 30-G3.	Check the device connected to output +LP-is working properly.
	R B	AB - Overload on output 30-13	Check the device connected to output 30-13 is working properly.

# 14. Troubleshooting

	<i>J</i>			
Problem	Possible cause		signal- ng	Operation
The control panel does not switch	No power supply.			Check the power supply cable and the F1 fuse.
on	Internal fault			Contact Technical Service
	No power.			Check the power supply cable and the F1 fuse.
	Short circuited accessories.	I5		Disconnect all accessories from terminals 0-1 or 0-30 (a voltage of 24V= must be present) and reconnect them one at a time.  Contact Technical Support Service
	Blown line fuse.			Replace fuse F1.
	Safety contacts are open.	1-6 68	1-8	Check that the safety contacts are closed correctly (NC).
The automation does not open or close	Safety contacts not correctly connected or self-controlled safety edge not functioning correctly.	A 0 A 1 A 3	1-6 1-8 68	Check connections to terminals 6-8 on control panel and connections to the self-controlled safety edge.
	Photocells activated.	1-6	1-8	Check that the photocells are clean and operating correctly.
	The safety edges connected to 6R and 8R are pressed or blocked	6R	BR	Check the resistance values of the safety edges.
	The automatic closure does not work.			Issue any command. If the problem persists, contact Technical Service
	Faulty motor or tripping of thermal switch.		1 <b>]</b> ] 1 [[	Check motor connection, if the problem persists, contact Technical Service.



Problem	Possible cause	Alarm signal- ling	Operation
External safety devices not acti- vating	Incorrect connections between the photocells and the control panel.		Check that I - 6 / I - B is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board.
9			Check the $\mathbf{HP} \rightarrow \mathbf{JB}$ and $\mathbf{HP} \rightarrow \mathbf{JB}$ setting
The automation opens/closes briefly and then stops.	There is a presence of friction.	MI OD OE OF OG	Manually check that the automation moves freely and check the R 1/R2 adjustment. Check that the limit switches, if installed, are working correctly Contact Technical Service
has limited range	The radio transmission is impeded by metal structures and reinforced concrete walls.		Install the antenna outside.  Replace the transmitter batteries.
tion moving.  The remote control does not work	No storage module or incorrect storage module.	RØ R3 RS	Switch the automation off and plug in the correct storage module. Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module.



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